

Variable Speed Drive

For 3 Phase AC Motor

NEW ND1 Series

- 1 Phase 220VAC Size 0.5 to 2HP
- 3 Phase 220VAC Size 3 to 5.5HP
- 3 Phase 380VAC Size 1 to 5.5HP



Your best choice Easy to use Space saving Energy saving



Features

- Latest IGBT technology
- New Compact design
- Low-noise motor operation thanks to high pulse
 Frequencies (Carrier frequency) 0 to 15 kHz and sound tone level 0- level 3)
- Frequency setting potentiometer is standard equipment
- 5 Digital input is programmable (Terminal FWD, REV,
 X1, X2 and X3) 20 Function assignment of input terminal
- Jog operation run by terminal (Jog FWD, Jog REV)
- The digital input terminals connection signal sink logic/source logic and NPN/PNP Sensor
- Two analog input
 - (0 to 10Vdc = Voltage input 12)
 - \bullet (4 to 20mA, 0 to 20mA = Current input C1)
- One programmable analog output
 (0-10Vdc, 0-20 mA = FMA) for meter
- One programmable relay output (30A/30B/30C)
- Output frequency 0.01 to 400.0 Hz
- 16 speed control & 15-step preset speed
 (Multistep frequency selection bit 0 to bit 3)
- Automation function (Pattern mode selection, stage time, Stage direction, 7 stage)
- Internal PID Controller for simple process control (PID Controller Group function)

Function code

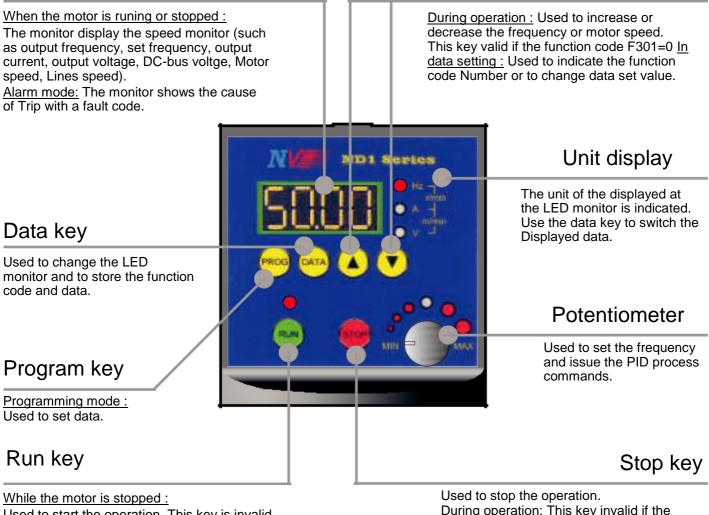
Function code group **Function code Function** Gr-1 F101-F118 **Motor Function** Gr-2 F201-F260 **Terminal Function** Gr-3 F301-F368 **Frequency Function** Gr-4 F401-F423 **Protective Function** Gr-5 F501-F522 **Special Function** Gr-6 F601-F636 **PID Controller** Gr-7 **Service Function** F701-F707

- Automatic torque boost
- Linear V/f characteristic
- Quadratic V/f characteristic
 - (variable torque load/Fan and Pump)
- Multipoint characteristic
 (programmable V/f characteristic)
- REV Phase Sequence Lock
- Flying restart
- Automatic restart following mains failure or fault
- Programmable acceleration/deceleration
 0 sec to 3600 sec and S-curve characteristics
- The alarm history for the 5 latest alarms is recorded
- 3 Jump frequency
- Short-circuit protection
- Stall prevention
- Overload warning (Lamp RUN Flash)
- Removable keypad

Keypad switches and functions

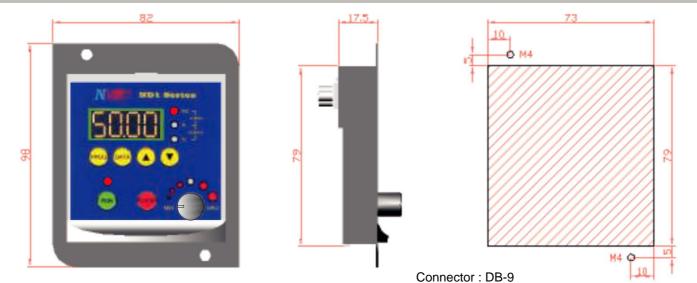
LED monitor

Up/Down keys

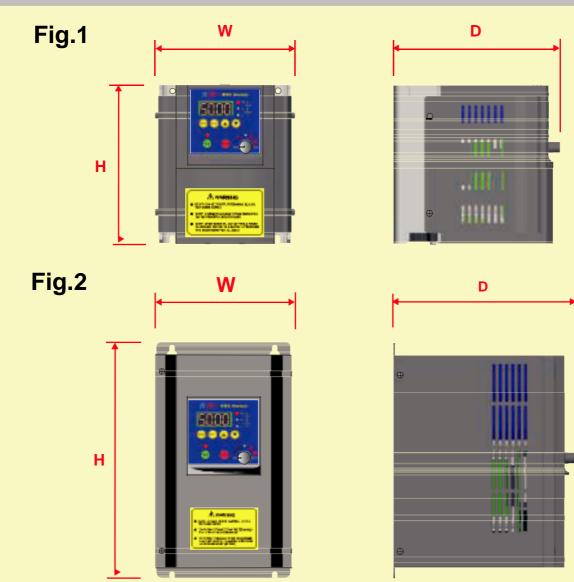


<u>While the motor is stopped :</u> Used to start the operation. This key is invalid if the function code F201=0 (operation by external signals). Used to stop the operation. <u>During operation</u>: This key invalid if the function code F201=0 (operation by external signals). <u>Alarm mode</u>: Resets a trip pervention mode.

Keypad mounting dimension

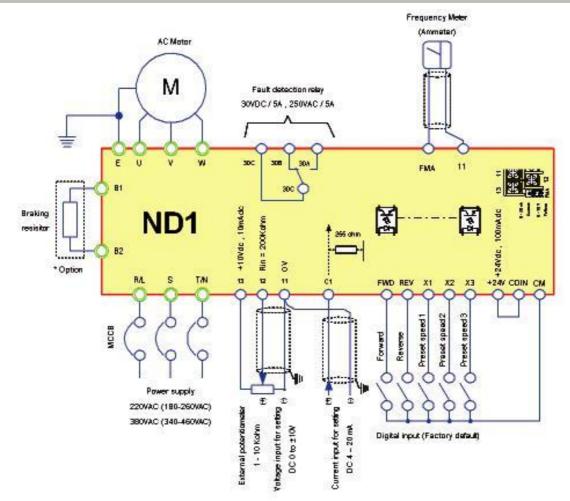


External Dimensions

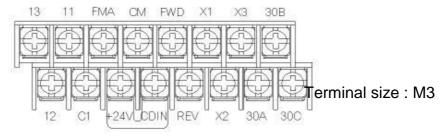


Power supply voltage	Model	HP	OUTPUT (A)	W x H x D (mm.)	Fig. Braking Unit	Fig. Cooling Method	Fig.
Single-	ND1-2-0A5	0.5	3.3			Self-cooling	
phase 220VAC	ND1-2-001	1	5.3	125 x 147 x 145	Not include		
	ND1-2-002	2	8.0				1
	ND1-4-001	1	3.5	128 x 147 x 155			
Three- phase	ND1-4-002	2	4.8	128 X 147 X 155		Forced air-cooled	
380VAC	ND1-4-003	3	6.2	-	Built-in		
	ND1-4-5A5	5.5	11		2		2
Three- Phase	ND1-2-003	3	11	131 x 225 x 175			2
220VAC	ND1-2-5A5	5.5	17.5				

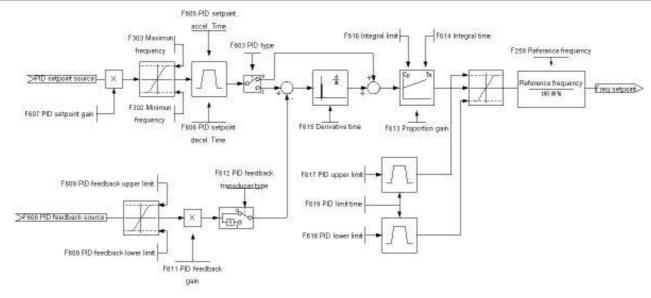
Wiring Diagram



Control circuit terminal (common to all the inverter models)



PID Control block diagram



Common specification

ltem		Specification			
	Control system	Sinusoidal PWM control			
Principal control ns	Rated output voltage	Adjustable within the range of 80 to 480V by correcting the supply (not adjustable above the input voltage)			
	Output frequency range	0.5 to 400.0 Hz default setting : 0.5 to 60 Hz , maximum frequency 10 to 400 Hz			
	Minimum setting steps of frequency	0.01 Hz: operation panel setting ,0.1Hz: analog input (when the max. Frequency is 100 Hz)			
	Frequency accuracy	Digital setting : within 0.01% of the max. frequency Analog setting : within 1.0 % of the max ferquency			
	Voltage/frequency characteristics	V/f constant ,variable torque , automatic torque boost .Base frequency (5-400Hz) adjusting frequency at start (0 – 20Hz)			
	Frequency setting signal	Potentiometer on the front panel ,external frequency potentiometer (connectable to a potentiometer with a rated impedance of 1 – 10 k),0 – 10Vdc (input impedance : 12 = 200kOhm),4 – 20 mAdc (Input impedance : 255 Ohm)			
	Frequency jump	Three frequencies can be set . Setting of the jump frequency and the range.			
	Upper and lower-limit frequencies	Upper-limit frequency: 0 to max frequency, lower-limit frequency: 0 to max frequency			
	PWM carrier frequency	Adjustable within a range of 1 to 15kHz (default : 10 kHz for 220V, 4kHz for 380V)			
ninstimate	PID control	Setting of proportional gain, intergral time ,differential time .			
	Acceleration / deceleration time	Selectable from among acceleration /deceleration times can be independently set with 4 type and selected with digital input signal 2 point (0.0 to 3600 sec) S-pattern value adjustable.			
	DC braking	Braking start-up frequency: 0 to 20.00 Hz, braking level : 0 to 30.0 % ,braking time : 0 to 600 seconds			
	Input terminal function (programmable)	Possible to select from among 20 functions , such as forward/reverse run signal input, jog forward /jog reverse run signal input, reset signal input .Logic selectable between sink and source by jumper position terminal CDIN,CM and +24V			
	Output terminal function (programmable)	Possible to select from 20 function, such as minimun/maximum frequency signal output, failure signal output, to assign to FL relay output.			
2	Forward /reverse run	The RUN and Stop key on the operation panel are used to start and stop operation respectively. The switching between forward run and reverse run can be done from two control unit : operation panel and terminal board.			
on	Jog run	Jog operation from the operation on the terminal board			
	Preset speed operation	Main ferquency speed ,+15-speed operation possible by changing the combination of 4 contacts on the terminal board			
	Auto-restart operation	In the event of a momentary power failure ,the inverter reads the rotation speed of the coasting motor and outputs a frequency appropirate to the rotational speed in order to restart the motor smoothly. This function can also be used when switching to commercial power.			
	Override function	The sum of two analog signal input and multistep speed by digital input can be used as a frequency command value			
	Failure detection signal	1c-contact output : (250Vac5.0A)			
Protective n	Protective function	Stall prevention, current limitation, over-current, output short circuit,over-voltage, under-voltage, overload protection by eletronic thermal function			
	Reset function	Function of resetting by closing contact 1a or by turning off power or the operation panel (Stop key).			
	Over load Capability	150% of rated current for 1 min.			
•	Alarms	Overvoltage, overload, under-voltage ,output short circuit			
Display function	Monitoring function	Such as set frequency ,output frequency ,motor speed ,load shaft speed ,output voltage, output current ,causes of past trip 0 through 4			
	Past trip monitoring function	Stores data on the past four trips:			
	Output for frequency meter	Analog output (full-scale DC 10Vdc or 20 mA)			
	4-digit 7-segments LED	Frequency : inverter setting ferqucency, output frequency Alarm: OC: Overcurrent, OU: Overvoltage,OH: Overheating of the heat sink,OL: Overload,SC: Output short circuit, HE: External fault,LU: Under voltage,			
	Indicator	Lamps indicating the inverter status by lighting ,such as RUN lamp , Hz lamp, Amp lamp, Voltage lamp,r/min lamp,m/min lamp, frequency setting pottentiometer lamp,			
Erwironm ents	Use environments	Indoor, not exposed to direct sunlight not exposed to direct corrosive gas not exposed to direct explosive gas			
	Ambient tempreature	-10 to 40 ° C			
	Storage tempreature	-10 to 60 ° C			